



## ATTACHMENT C

### Amendments to the Claims

*This listing of claims will replace all prior versions, and listings, of claims in the application.*

1-31. (Canceled)

32. (New) A demountable drive mechanism for coupling to a drive shaft of an operating device, the drive mechanism being directly securable to the drive shaft to cause the drive shaft to rotate, the drive mechanism comprising a geared electric motor having an output for coupling to the drive shaft, the drive mechanism having a torque arm adapted to engage a reaction surface so that the electric motor can impart torque to the drive shaft, and control means to control operation of the electric motor, the electric motor having an operating current that is monitored in small time increments wherein a maximum allowable current is set as a percentage above the operating current being monitored so that should there be a significant and rapid increase in operating current the motor shuts down.

33. (New) The demountable drive mechanism according to claim 32 wherein the torque arm is mounted no the drive mechanism parallel to the drive shaft.

34. (New) The demountable drive mechanism according to claim 32 wherein the electric motor is powered by at least one battery.

35. (New) The demountable drive mechanism according to claim 32 wherein solid state relays are interposed between an electric input of the electric motor and the electric motor, the solid state relays causing voltage of the electric motor to pulse and cap an operating current peak when the motor is first switched on.

36. (New) The demountable drive mechanism according to claim 35 wherein the solid state relays comprise field effect transistors.

37. (New) The demountable drive mechanism for coupling to a drive shaft of an operating device, the drive mechanism being directly secured to the drive shaft to cause the drive shaft to rotate, the drive mechanism comprising a geared electric motor having an output for coupling to the drive shaft, the drive mechanism having a torque arm adapted to engage a reaction surface so that the electric motor can impart torque to the drive shaft, and control means to control operation of the electric motor, wherein solid state relays are interposed between an electric input of the electric motor and the electric motor, the solid state relays causing voltage of the electric motor to pulse and cap an operating current peak when the motor is first switched on.

38. (New) The demountable drive mechanism according to claim 37 wherein the torque arm is mounted on the drive mechanism parallel to the drive shaft.

39. (New) The demountable drive mechanism according to claim 37 wherein the electric motor is powered by at least one battery.

40. (New) The demountable drive mechanism according to claim 37 wherein the electric motor has an operating current that is monitored in small time increments wherein a maximum allowable current is set as a percentage above the operating current being monitored so that should there be a significant rapid increase in operating current the motor shuts down.

41. (New) The demountable drive mechanism according to claim 37 wherein the solid state relays comprise field effect transistors.